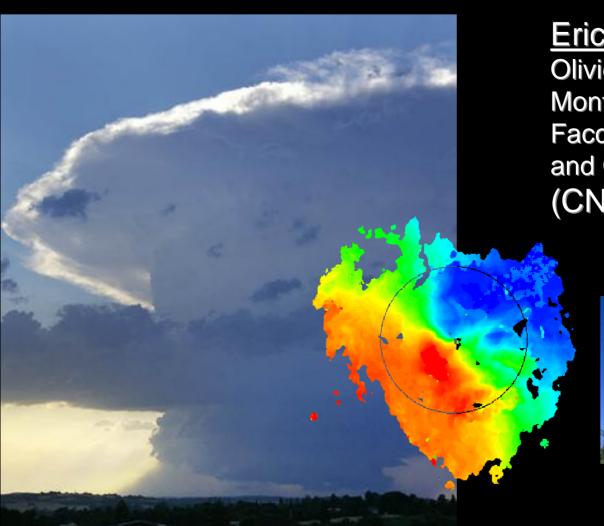
Assimilation of radar data in the AROME model at Météo-France



Eric Wattrelot,
Olivier Caumont, Thibaut
Montmerle, Claudia
Faccani, Marian Jurasek
and Günther Haase
(CNRM)







- Context and Introduction.
- Basic theory of the two measurements: radial wind and reflectivity
- Sources of measurement errors: need for pre-processing radar data.
- The specific radar product for AROME
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- Conclusions and perspectives



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Context and Introduction

The AROME project ...

- The mesoscale AROME model and its non-hydrostatic physic have the capability to simulate and to forecast dangerous mesoscale convective events as storms, wind bursts and therefore initial unexpected floods...
- However, previous studies have shown that good initial conditions were important in order to improve mesoscale convection forecasts (see presentation before by Pierre Brousseau…).
- Accordingly, there is need for using high density obervations...
 - ⇒ Radar data from the french ARAMIS network can play a key role by providing information about the low level horizontal wind and the precipitating pattern within precipitating systems

Assimilation strategy: observation operator and 3DVar...

- Radial velocity observation operator is based on the horizontal wind field: impact studies have been carried out using the 3DVar AROME and long period of monitoring in pre-operational AROME model have been done
- Reflectivity observation operator needs a complete description of warm and cold hydrometeors: realistic simulation can be obtained only with AROME. But if reflectivities provide useful information, assimilation of rain is very difficult (not a model variable) and probably not very useful (rainfalls have a short shelf life). Therefore, there is need for a specific 1D+3DVar assimilation.

Context and Introduction

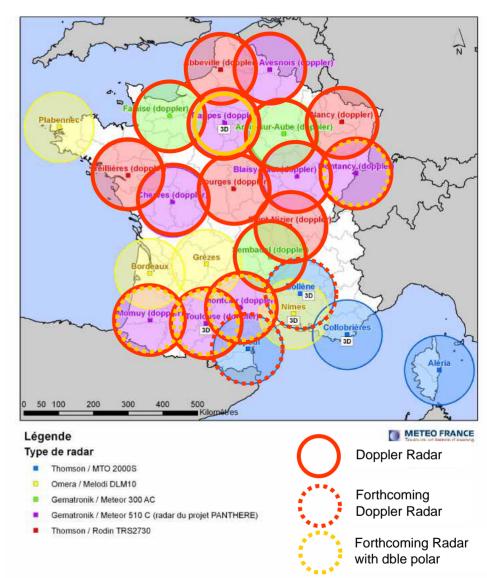
The ARAMIS radar network

Current status: high spatial and time resolutions...

- 24 radars from which 17 Doppler C-band Radars performing between 3 and 14 PPIs (Plan Position Indicator: constant elevation)/ 15' and 1km horizontal resolution
- 1 double polarimetric (Trappes)

Expected at the end of 2008:

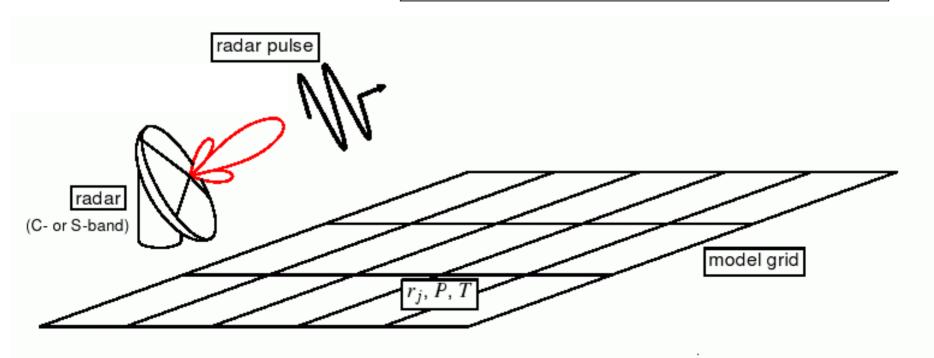
- All the radar network will be Doppler radars
- 4 with double polar (interesting for distinguish different shapes of hydrometeors.



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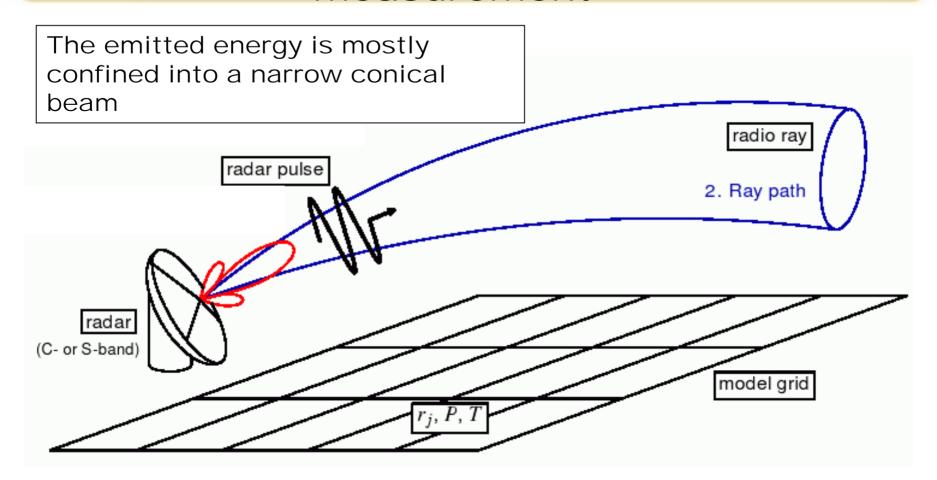


The radar antenna emits a horizontally polarized electromagnetic pulse.

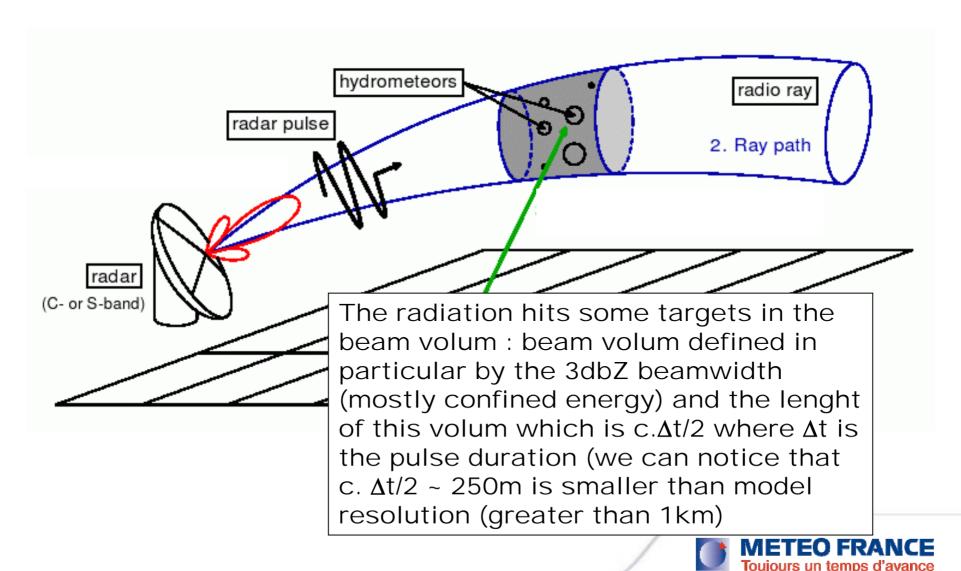


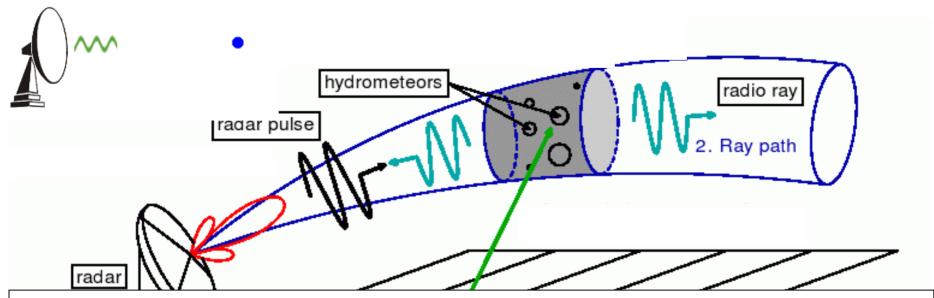








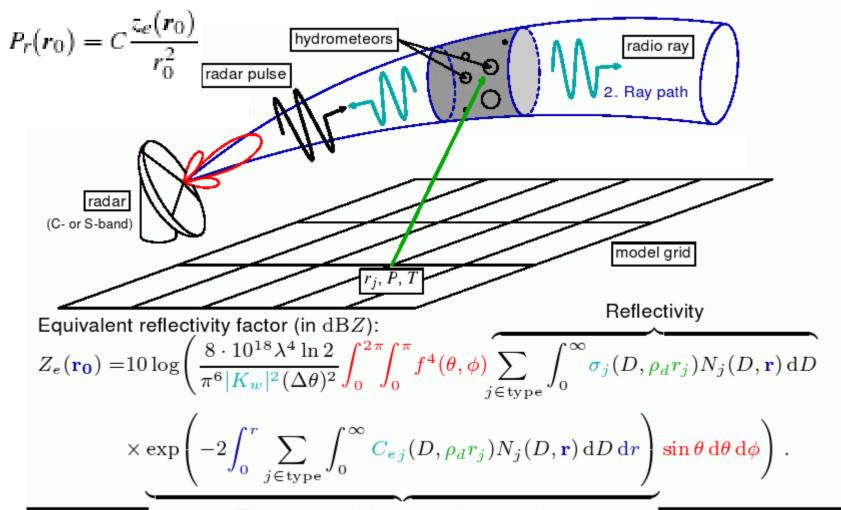




A part of the radiation is scattered in all directions and attenuated by the targets.

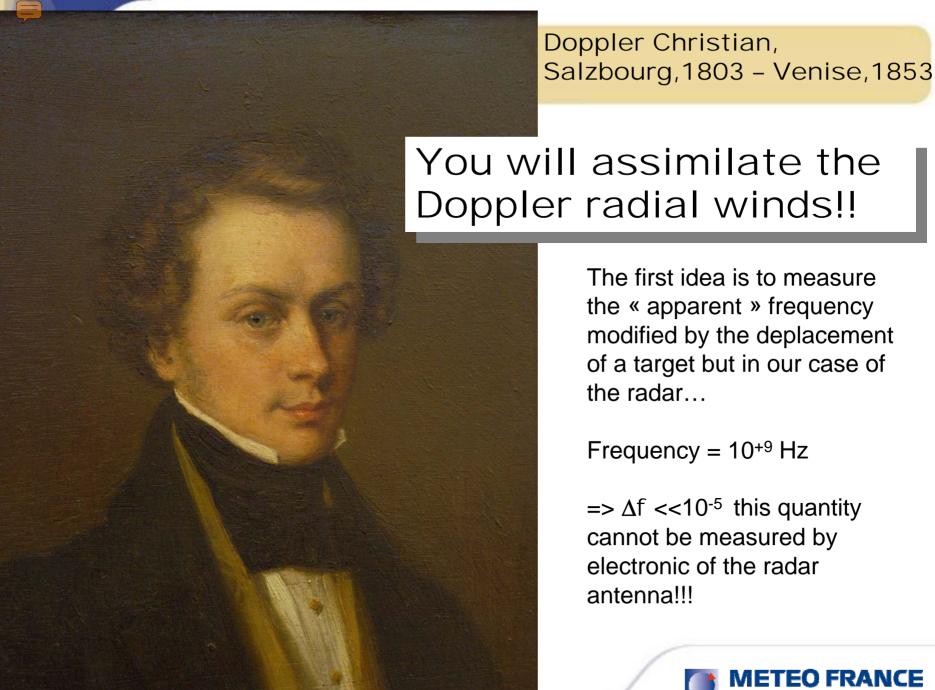
Another part of the energy of the radiation is backscattered in the direction of the radar and measured by the radar in reception mode. This quantity Pr depends on the nature, the shape and the size of the targets but also on the characteristics of the radar...

We can know the location of the beam volum by measuring the time T between the emission and the reception: d=c.T/2 (distance between radar and hydrometeors).



Two-way path-integrated attenuation

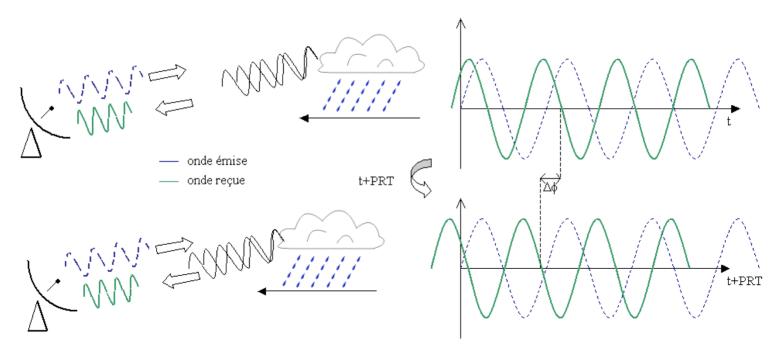






The basic theory of the Doppler measurement

A impulsed wave is emitted each period PRT (Pulse Repetition Time). PRT= 3ms



The deplacement of the target induces a variation of phase between the successive impulses => radial velocity measurement:

$$Vr = \frac{dr(t)}{dt} = \frac{\lambda \Delta \Phi}{4\pi PRT}$$
 r(t): distance radar- precipitation

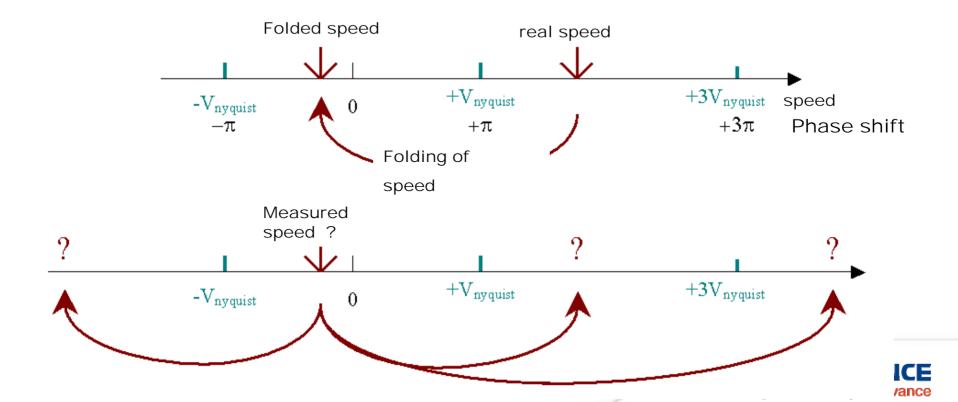
METEO FRANCE Toujours un temps d'avance



Aliasing of the speed

The signal is sampled at an emitted frequency PRF (Pulse Repetition Frequency). If the phase shift between two pulses exceeds π , the measure of speed can be ambiguous. The speed is folded or aliased in the interval [- $V_{nvquist}$].

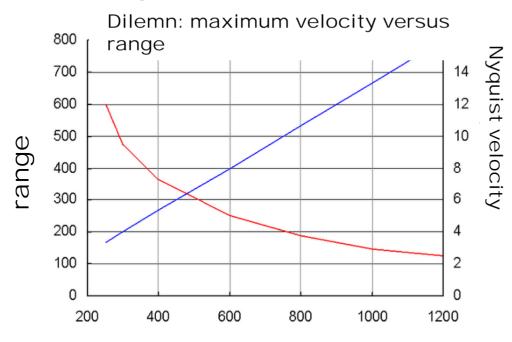
Typically, V_{nyquist}=5m/s.



The basic theory of the Doppler measurement

We can increase the non-ambiguous Nyquist velocity with a PRT very small: $Vr = \Lambda / (4PRT)$. However, the range of reflectivity is directly proportional to the duration between two successives impulsed waves (because of need for location): d = c.PRT/2

Accordingly, there is a compromise to find... and we can't increase the maximum velocity.

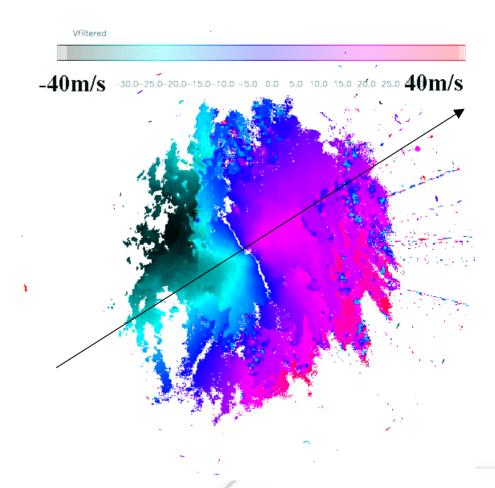


1/PRT: impulsed repetitions



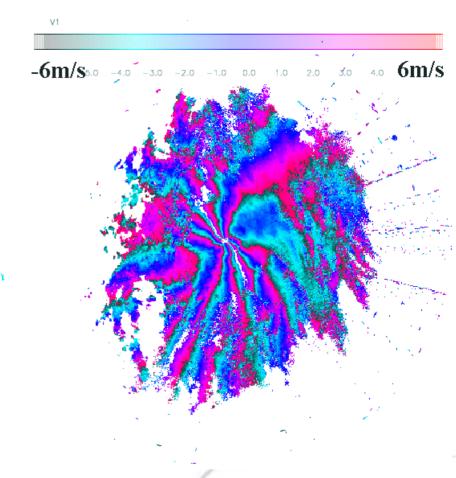
Real radial wind map

- Map of 512km by 512km
- Resolution of 1km²





Folded radial wind map

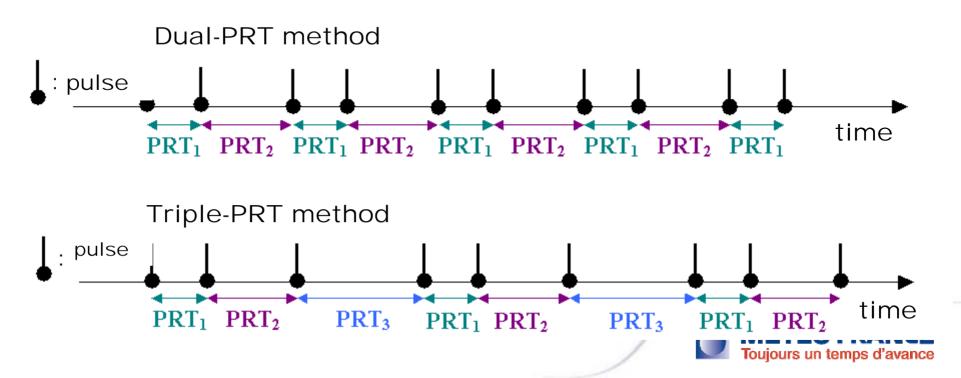




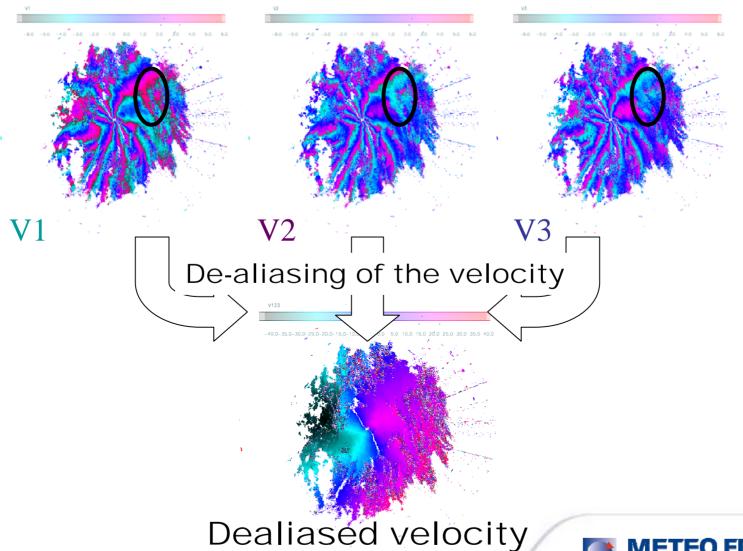
The dual-PRT and triple-PRT method

(Tabary & al. 2005 et 2006)

The methods are to combine several pulses at two or three different PRT alternatively. The differences of aliasing velocities (for the different PRT) allow to estimate real radial velocity of targets...



Triple-PRT method





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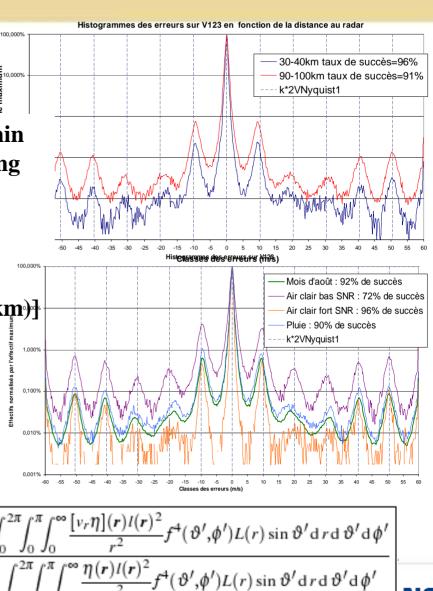
Quality of the Doppler measurement

The quality of the Doppler measurement depends on:

> 1. Number of samples available within the pixel (quantity linearly decreasing with range)

2. The signal-noise-ratio: $SNR(dB)=Z(dBZ)+20*log_{10}[100/r(km)]$

- 3. The spectral width (which is only just beginning to be calculated operationally)
- 4. The measurement is representative of the size of the beam volum: it increases with range, so the incertitude as well)



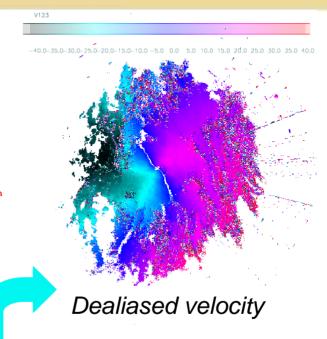
$$v_r(\mathbf{r}_0) = \frac{\int_0^{2\pi} \int_0^{\pi} \int_0^{\infty} \frac{[v_r \eta](\mathbf{r}) l(\mathbf{r})^2}{r^2} f^4(\vartheta', \phi') L(r) \sin \vartheta' \, \mathrm{d} r \, \mathrm{d} \vartheta' \, \mathrm{d} \phi'}{\int_0^{2\pi} \int_0^{\pi} \int_0^{\infty} \frac{\eta(\mathbf{r}) l(\mathbf{r})^2}{r^2} f^4(\vartheta', \phi') L(r) \sin \vartheta' \, \mathrm{d} r \, \mathrm{d} \vartheta' \, \mathrm{d} \phi'}$$

Pre-processing of the radial wind

Doppler velocity dealiasing method

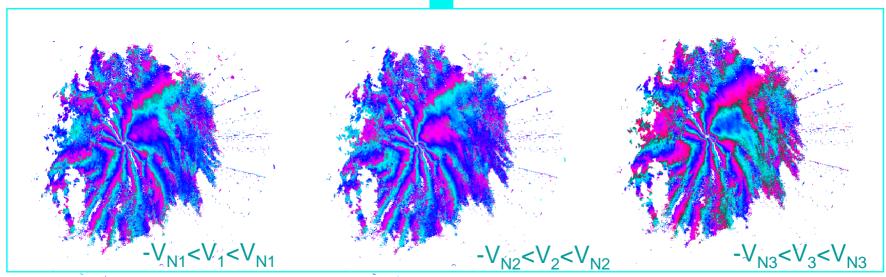
Use of a staggered triple-PRT (Pulse Repetition Time) scheme

 \Rightarrow 3 different Nyquist velocities V_{Ni}

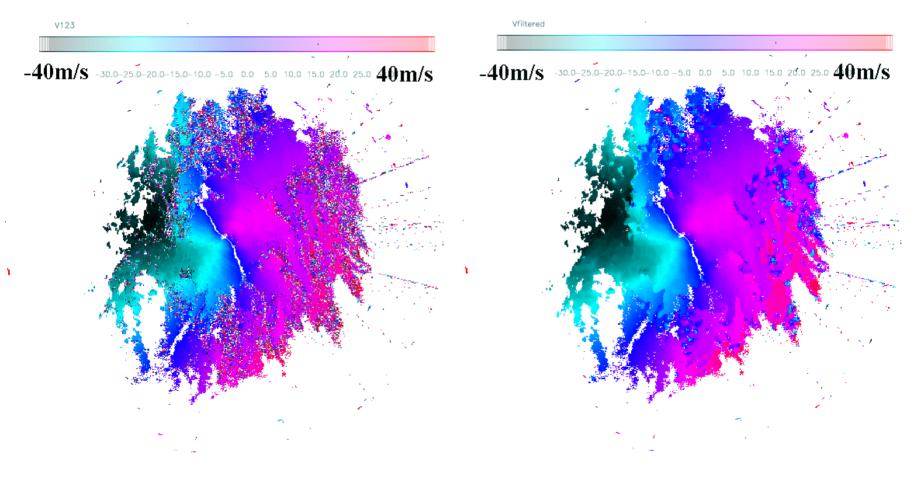


But still some noisy pixels...

⇒ Need for filtering



Reference velocity... some noisy pixels : need for filtering



Dealiased velocity

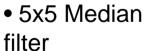
Filtred dealiased velocity



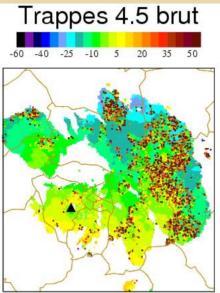


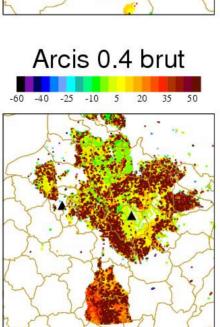
Pre-processing of the radial wind

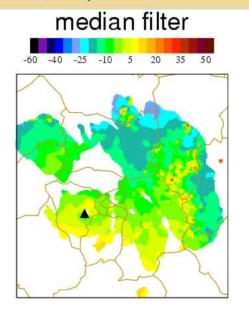
(Faccani & al, 2007)

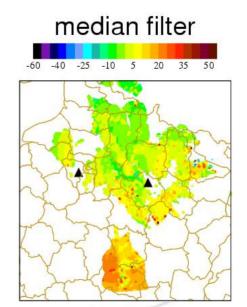


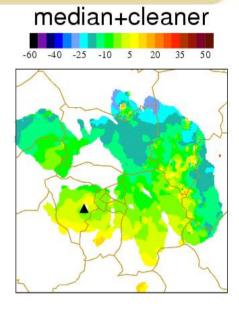
• 3x3
« cleaner »
filter
(replacement
of pixels with
large error
compared to
the
surrounding
pixels by the
median of the
sorted values)

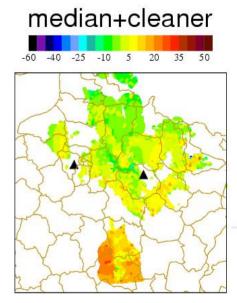








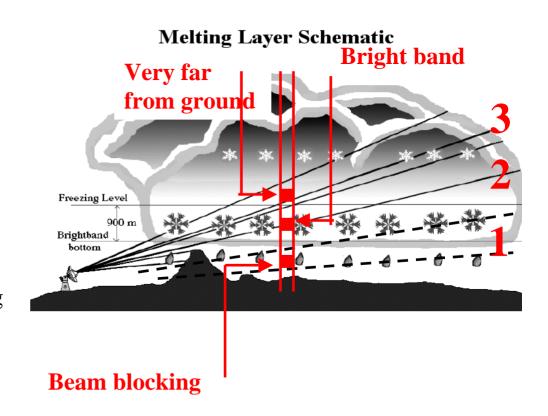




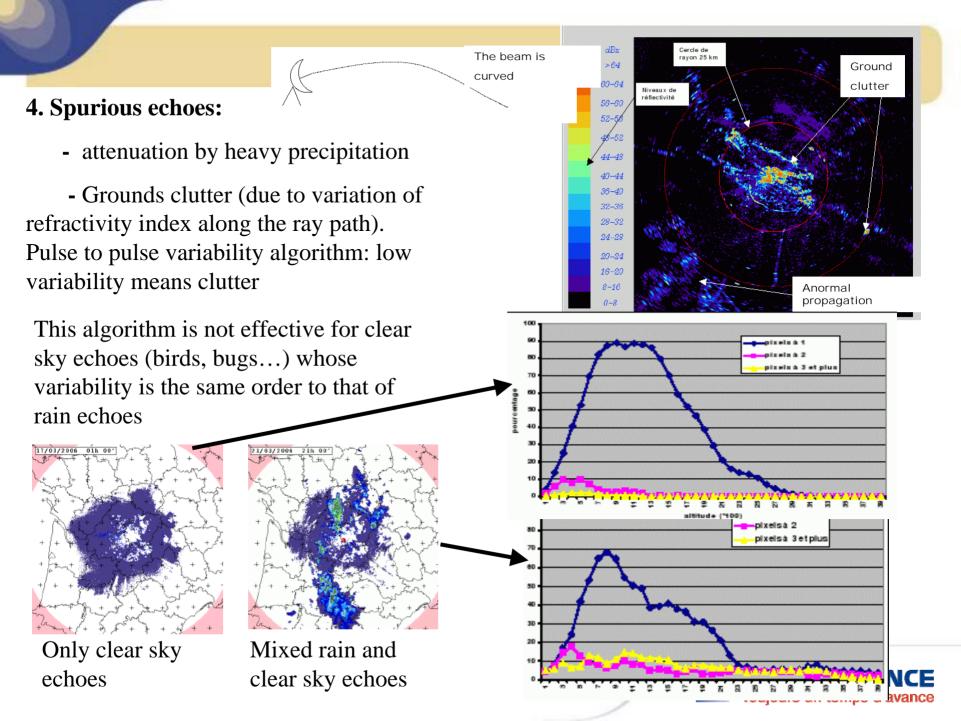
Quality of the reflectivity measurement

The quality of the reflectivity measurement depends on:

- 1. Clutter on orography and partial beam blocking behind mountains
- 2. Bright band: difficult to simulate
- **3. Altitude of reflectivities:** possible problem for ground rain-rates but not for reflectivities. But error positionning increasing with altitude because of broadening of the beam and of a constant refractivity index along the ray path

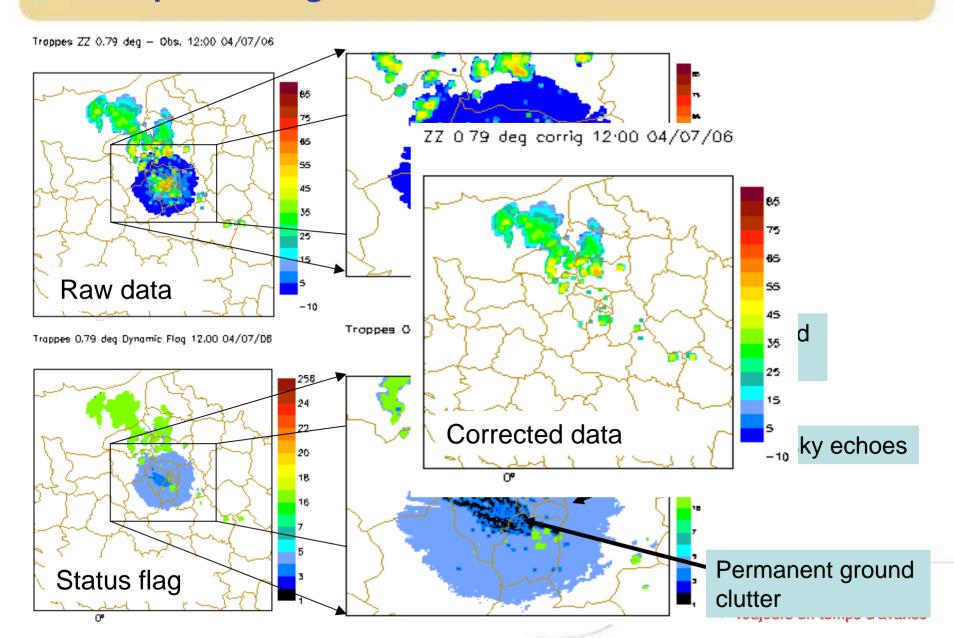








Pre-processing of the reflectivities: Gross error removal

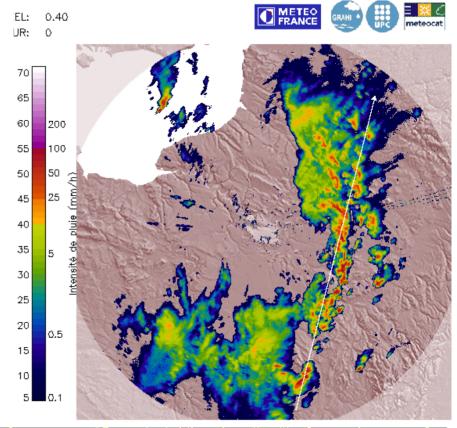


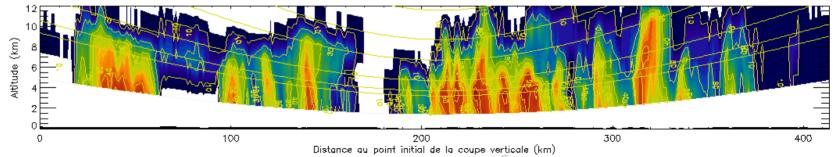
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Radar product for AROME

- Data (Z, Vr, Status) provided in BUFR format at 1 km horizontal resolution for 24 Radars so far (Status= one byte decomposed in two parts of 4 bits: information on spurious echoe and attenuation)
- \Rightarrow ~120 elevations x ((512)² x 3) = 94.371.840 pixels for one assimilation time!
- ⇒ A lot of data and of headaches to manage!

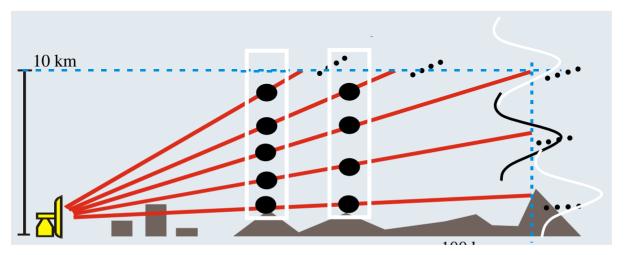






Radar product for AROME... in the model

- ~ 94.371.840 pixels for one assimilation time!
- \Rightarrow 6.291.456 columns in the model



Using columns of observations in model

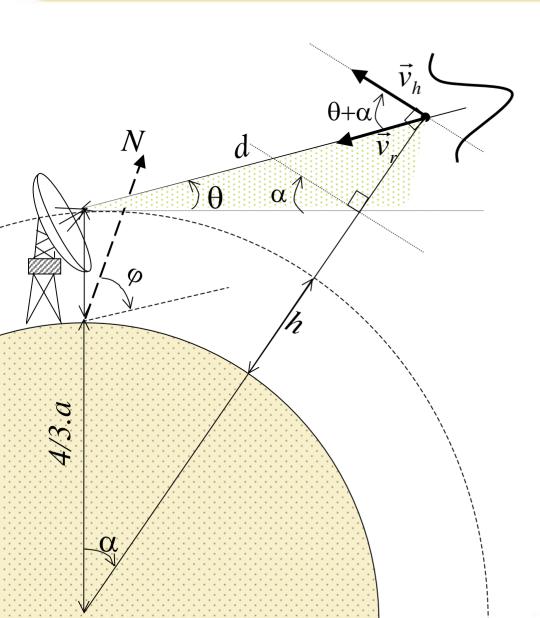
- Radar observations considered as profiles in the model
- Altitudes of the pixels calculated considering a constant refractivity index along the ray path (i.e using the approximation of the Earth's effective radius: consistent with observation operator, see hereafter)
- This last approximation is also coherent with the non-horizontal integration of the beam because of parallel purposes (we cannot simulate anormal propagation and attenuation!!)

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Doppler wind observation operator

(Caumont & al, 2006 and Salonen & al, 2003)



Follows closely HIRLAM's:

- Bi-linear interpolation of the simulated (u,v) (gate length smaller than model resolution: no horizontal integration)
- Projection of (u,v) towards the radar $v_h = u \sin \varphi + v \cos \varphi$
- Projection of v_h on the slanted direction of the radar beam (using the earth's effective radius model)

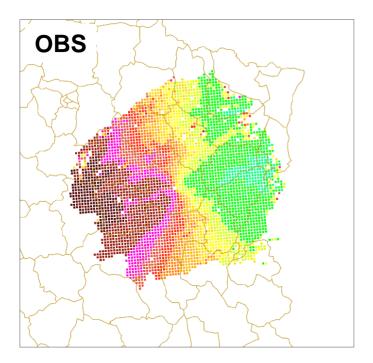
$$v_r = v_h \cos(\theta + \alpha)$$

$$\alpha = \arctan\left(\frac{d\cos\theta}{d\sin\theta + \frac{4}{3}a + h}\right)$$

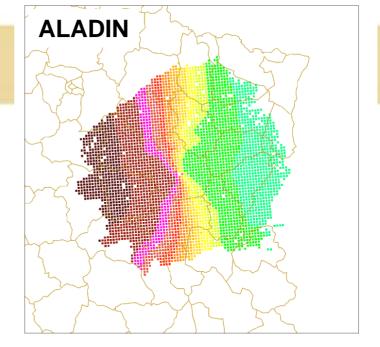
- No fall speed correction
- Side lobes contributions neglected
- Broadening of the radar beam simulated by a Gaussian function (Probert-Jones, 1962)
- TL/AD

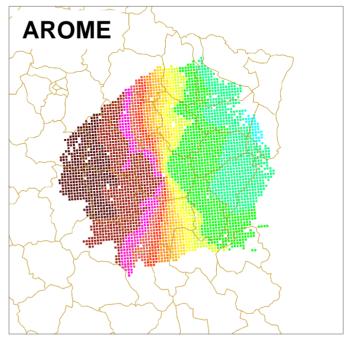
Exemple de vents radiaux simulés :

Blaisy – élévation 1°



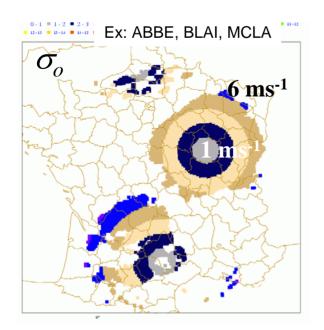
Convention: $Vr > 0 \Rightarrow vers le radar$







.60-.50 = .20-.40 = .40-.30 = .30-.20 = .20-.15 = .15-.10 = -10-.5 = .5-.0 = 0-.5 = .5-.10 = 10-.15 = .15-.20 = .20-



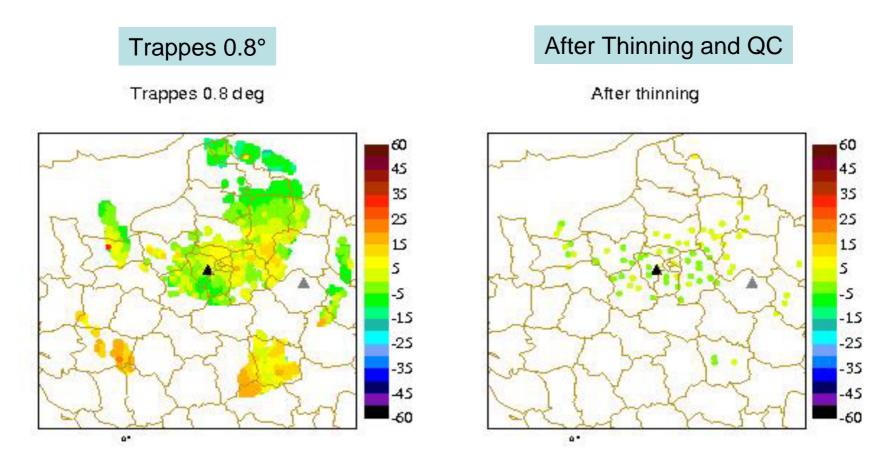
Screening quality control:

- error with range and broadening of the main lobe with range:
- σ_0 depends linearly on the range
- check only the departures (observation minus guess) between +/- 20 ms⁻¹



Thinning

- To avoid observation error correlations between adjacent pixels
- Sorting criterion: # of elevations, (minimum cumulated innovation)

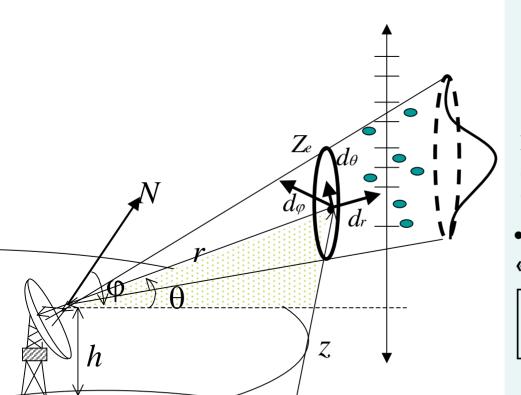




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Reflectivity Observation operator (Caumont & al. 2006)



- Bi-linear interpolation of the simulated hydrometeors (T,q, q_r, q_s, q_g)
- Compute radar reflectivity on each model level

$$\eta(r) = \sum_{j=rain,snow...} \sigma j(D,r).Nj(D,r)dD$$

$$Microphysic Scheme in$$

$$Backscattering cross AROME$$

$$section: Rayleigh$$

$$(attenuation neglected) Diameter of particules$$

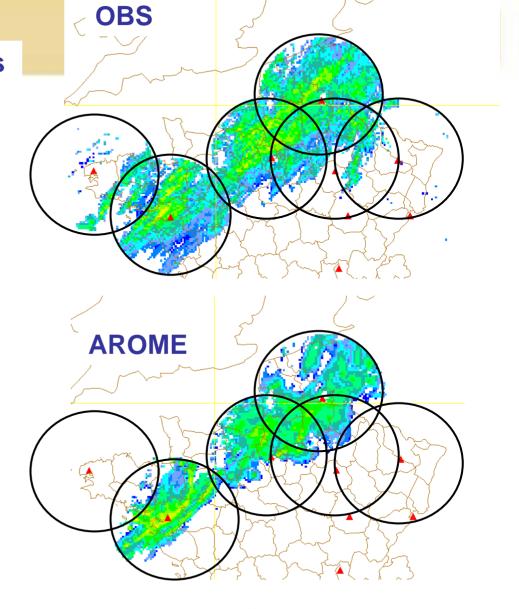
 Simulated Reflectivity factor in « beam volum bv»

$$Z_e = 10\log(\int_{bv} \eta(r).f^4(\theta,\varphi).dr.d\theta.d\varphi)$$

Resolution volum, ray path: standard refraction (4/3 Earth's radius) and gate length is 250m, smaller than model resolution

Antenna's radiation pattern: gaussian function for main lobe (side lobes neglected) Exemple: cold front, reflectivities 160 kms around different radars on the north of France

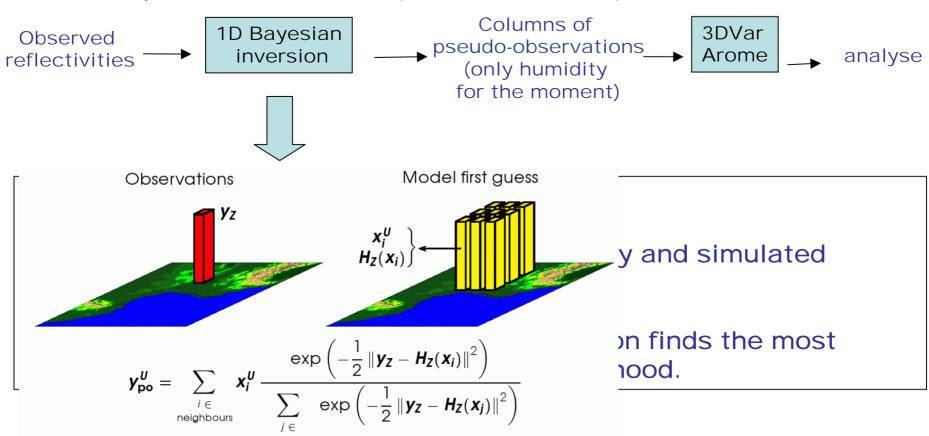
Counterpart of simulated Reflectivities by AROME:





Radar reflectivities assimilation

Basic theory of 1D+3DVar method (Caumont & al. 2006):



 \mathbf{y}_{po}^{u} : column of pseudo-observed relative humidity,

 $\dot{y_z}$: column of observed reflectivities,

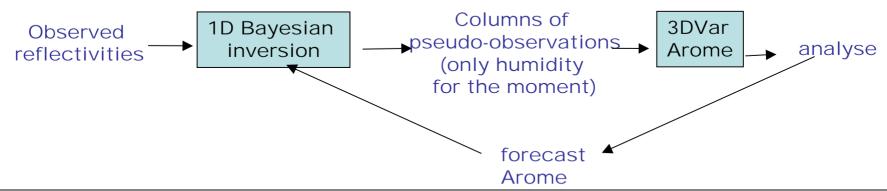
 \mathbf{x}_{i}^{U} : column of relative humidity,

 $H_Z(x_i)$: column of simulated reflectivities.



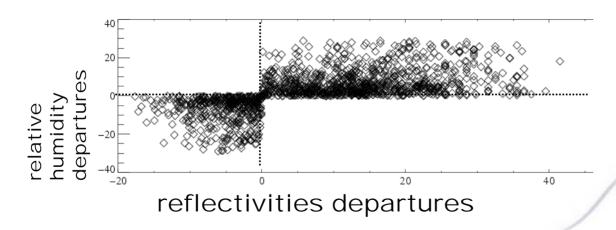
Radar reflectivities assimilation

Basic theory of 1D+3DVar method:

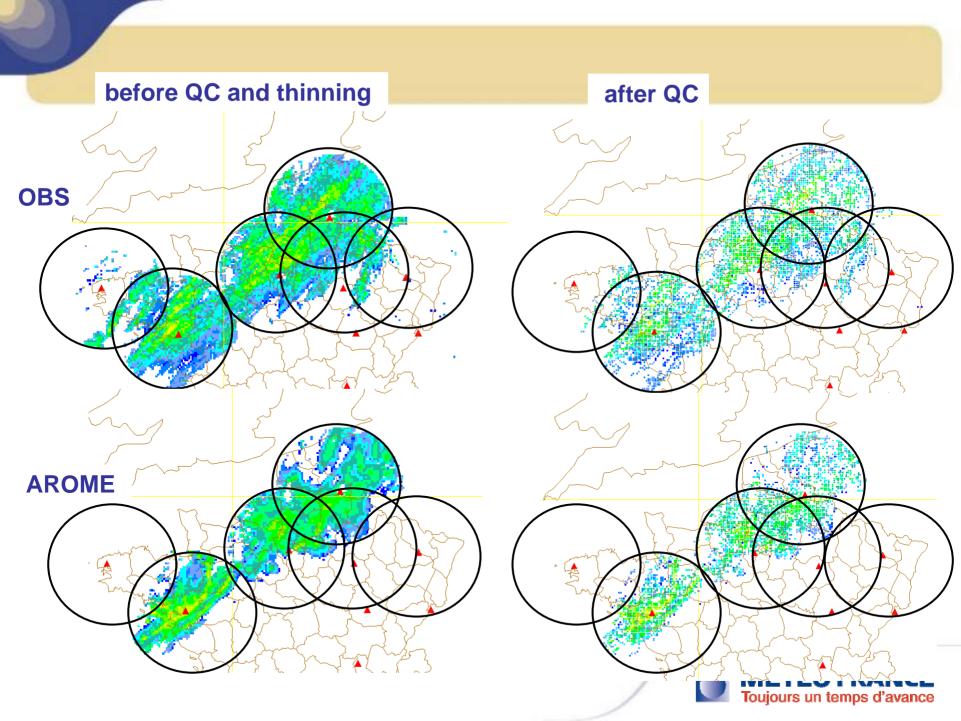


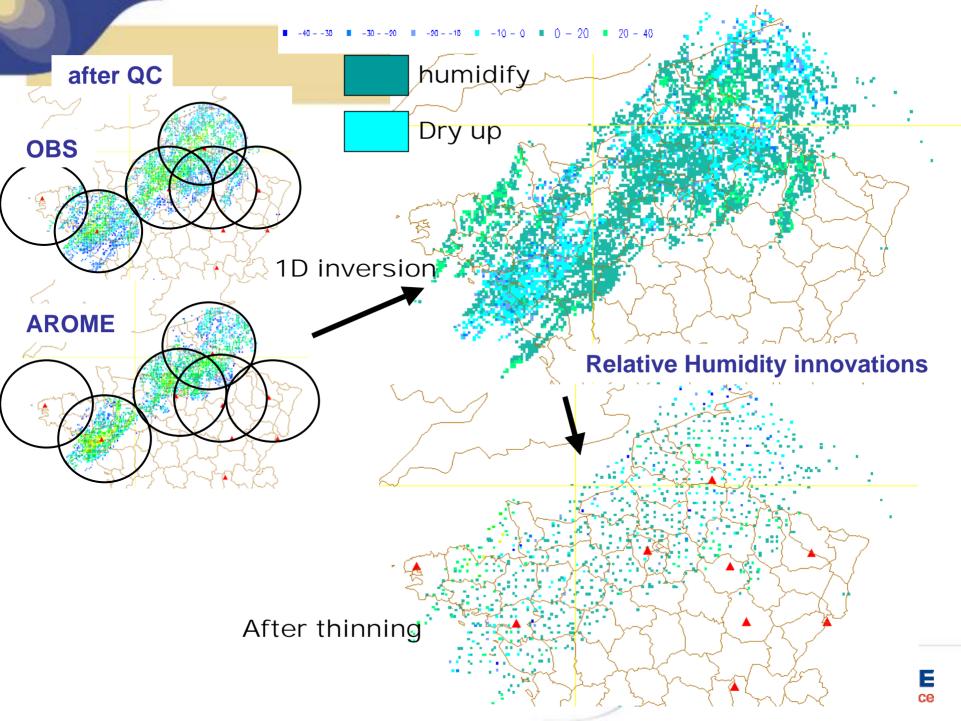
Quality control which takes into account :

- >The reflectivities departures
- >The pseudo-observations relative humidity departures
- ➤ Consistency between the reflectivities departures and the humidity retrievals departures (test of convergence of the 1D Bayesian inversion)









Outlines

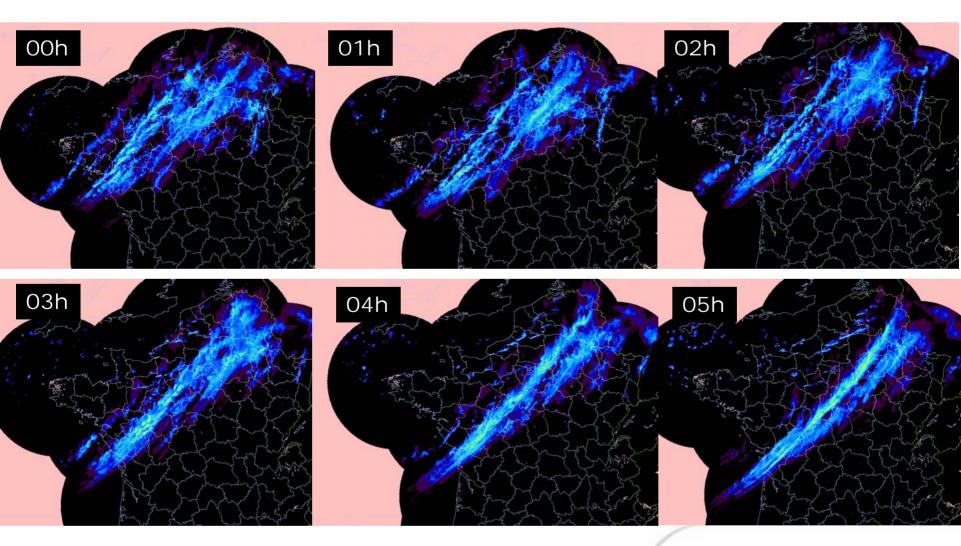
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1st decembre 2007



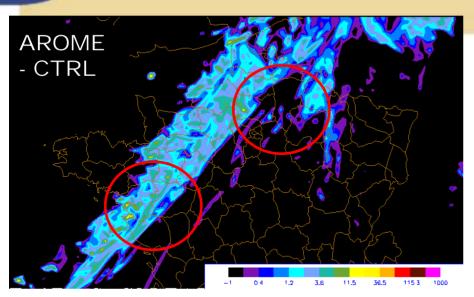
Narrow band of cold front: chronology with radar composite

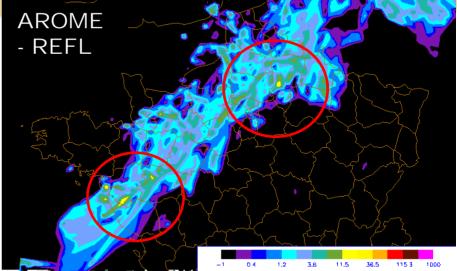


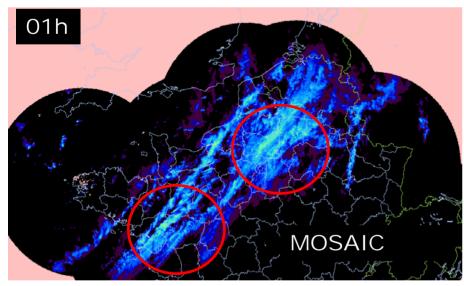


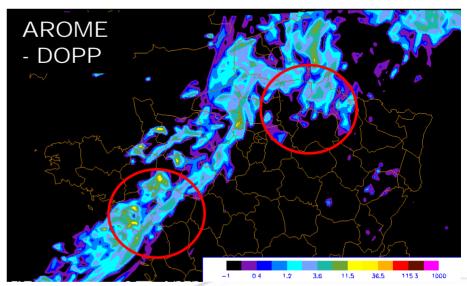
simulated reflectivities

r00 - 1 hour forecast



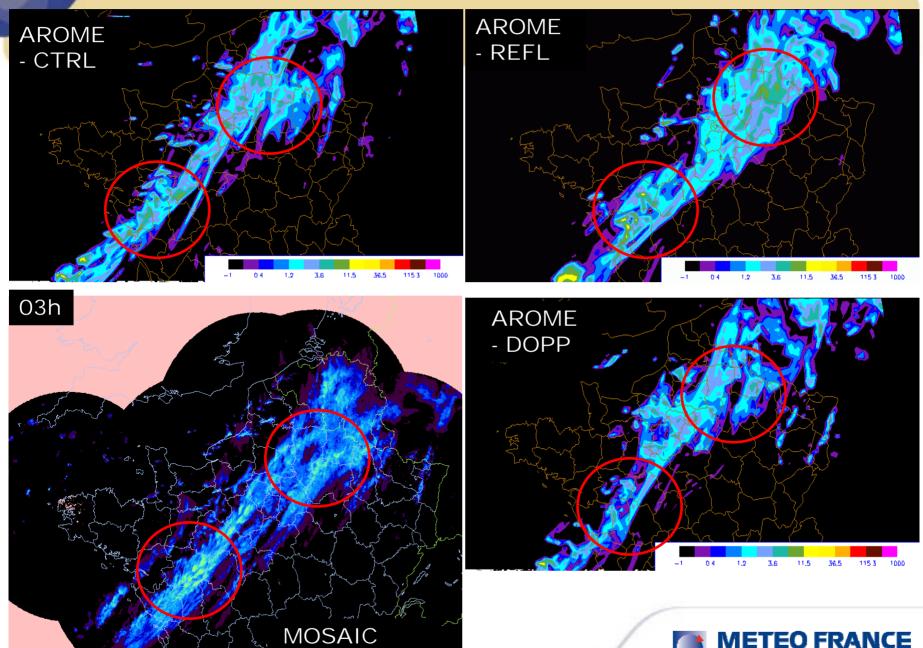




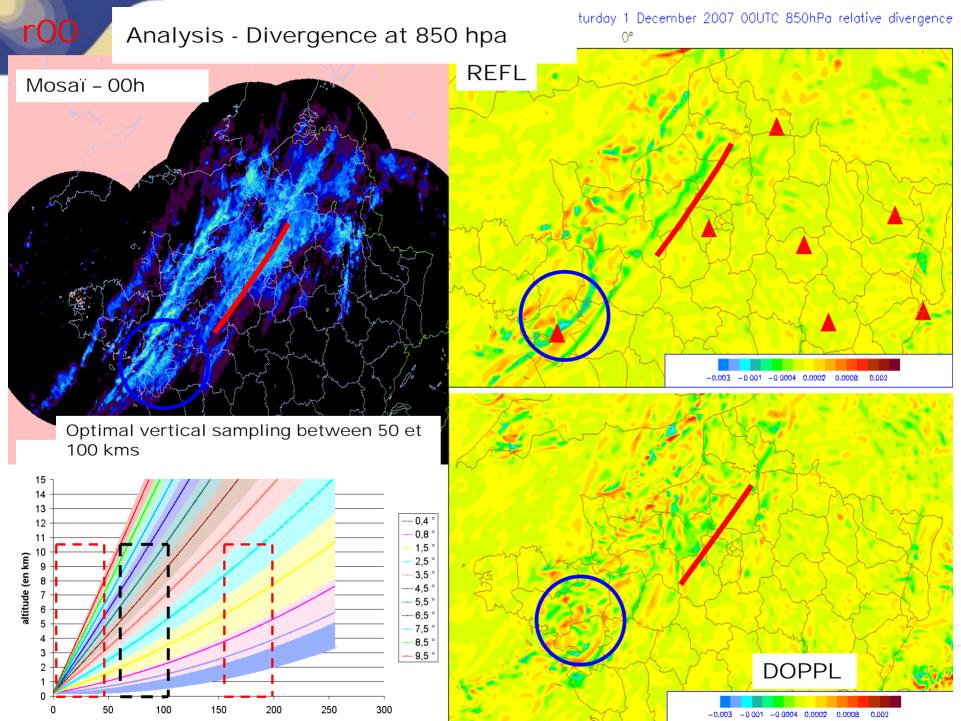




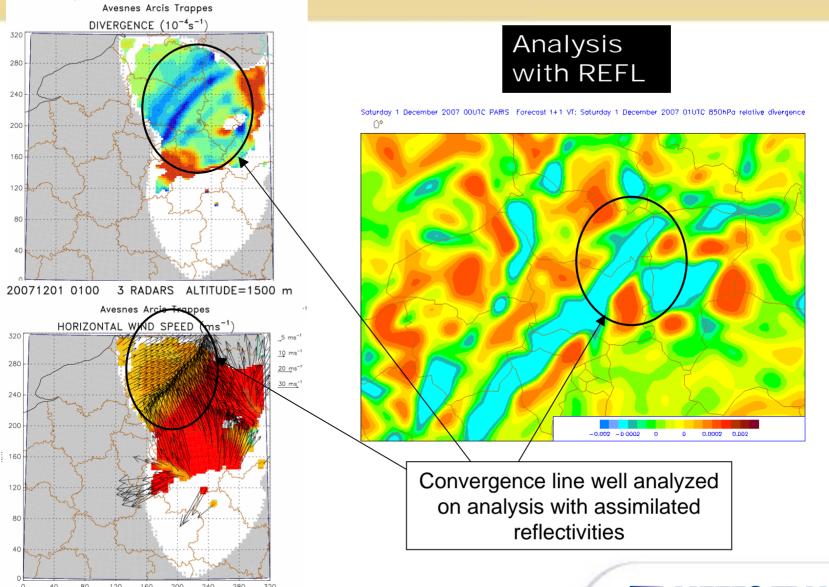
r00 - 3 hour forecast



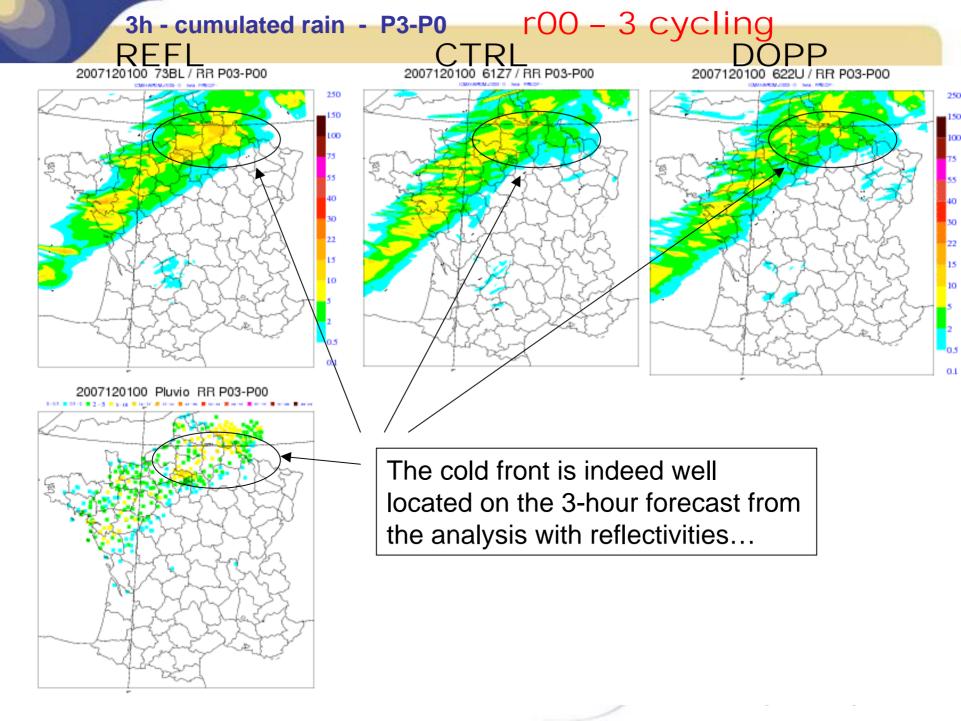




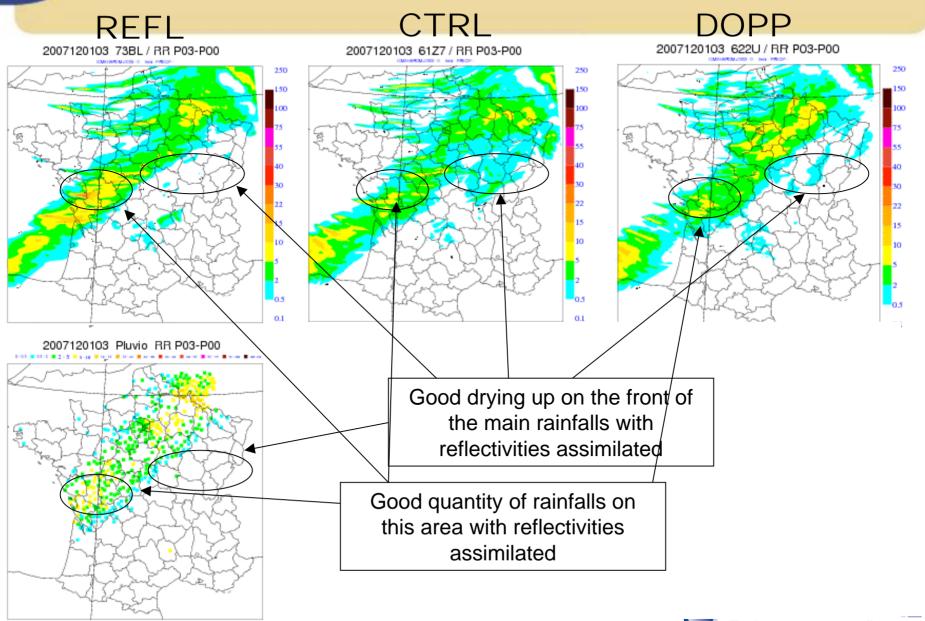
Checking with « MUSCAT » software which consists of independent reconstructed wind fields with several superimposed radars (Bousquet al. 2008)





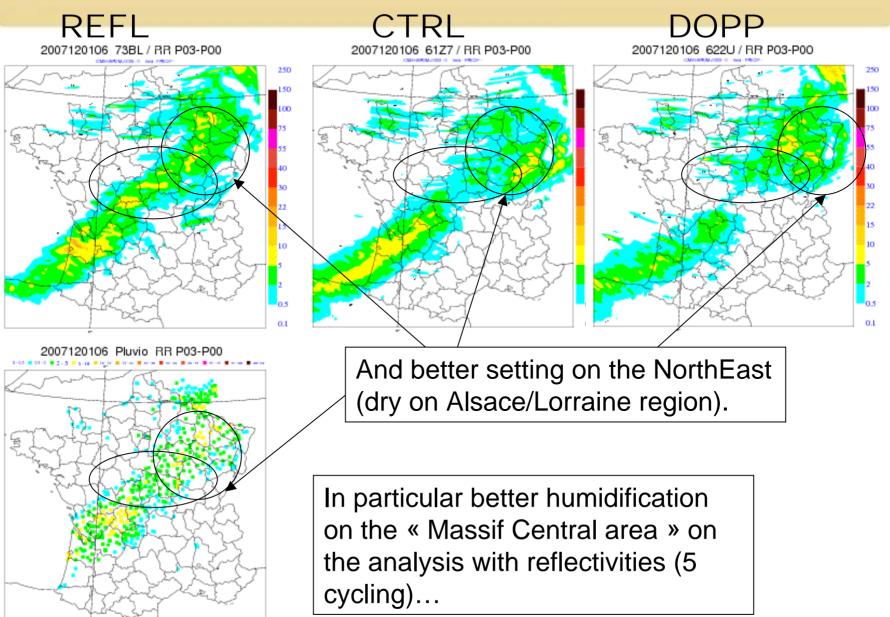


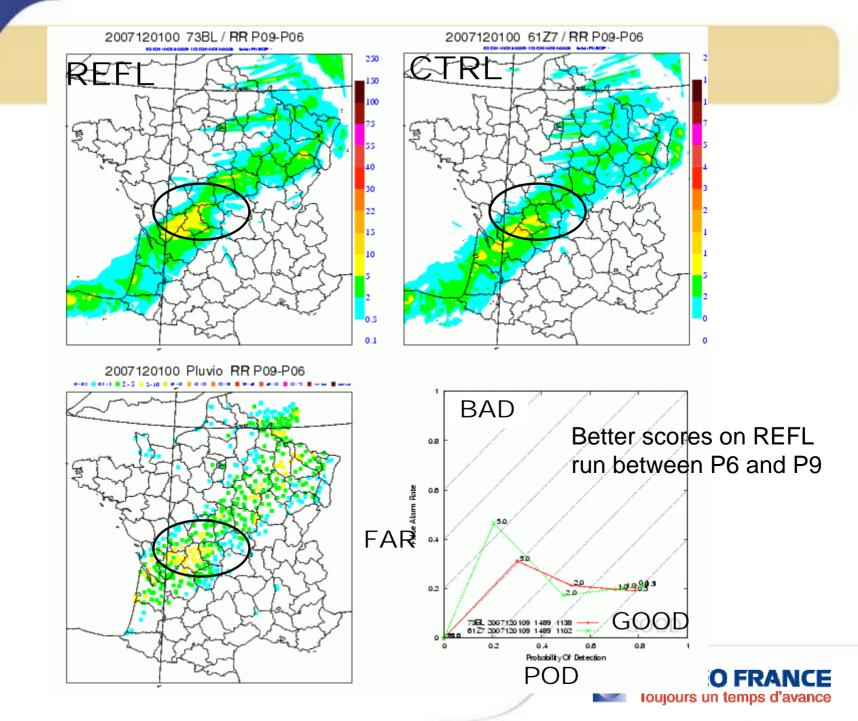
3h - cumulated rain - P3-P0

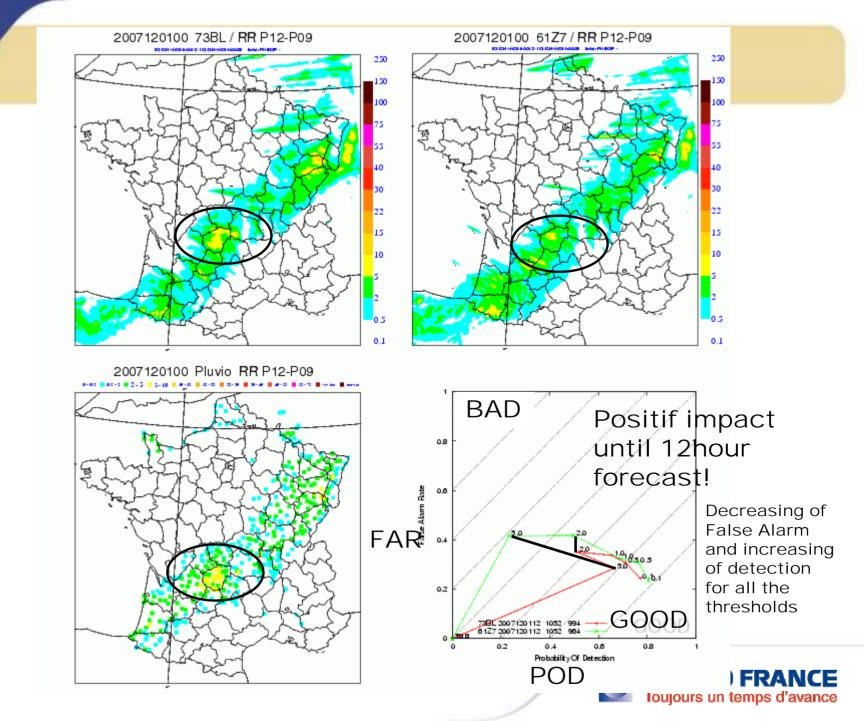


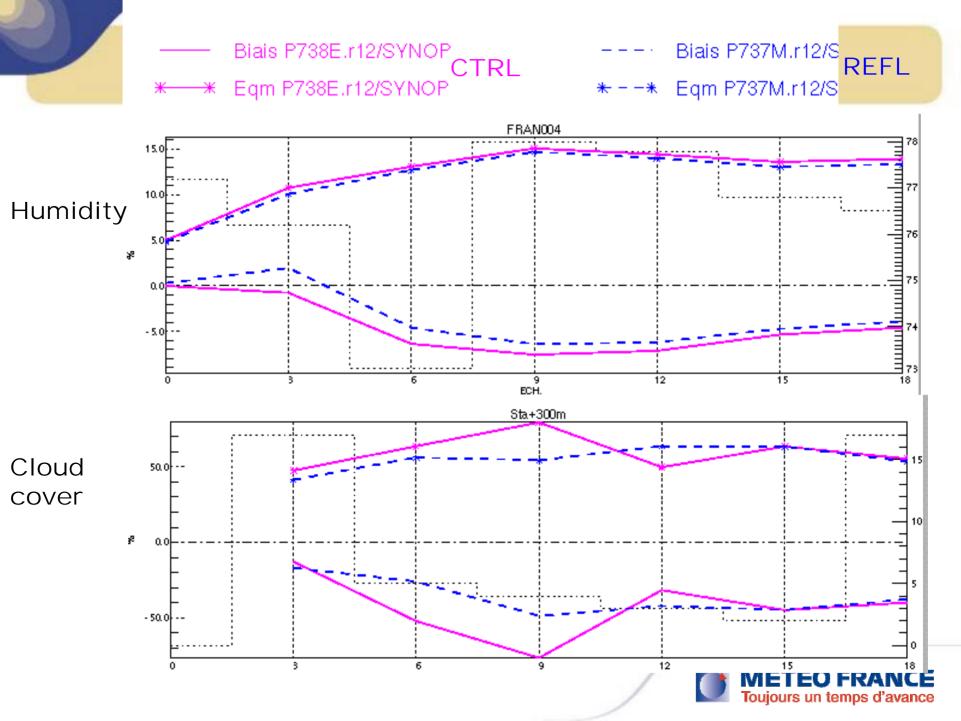
r06 - 5 cycling

3h - cumulated rain - P3-P0







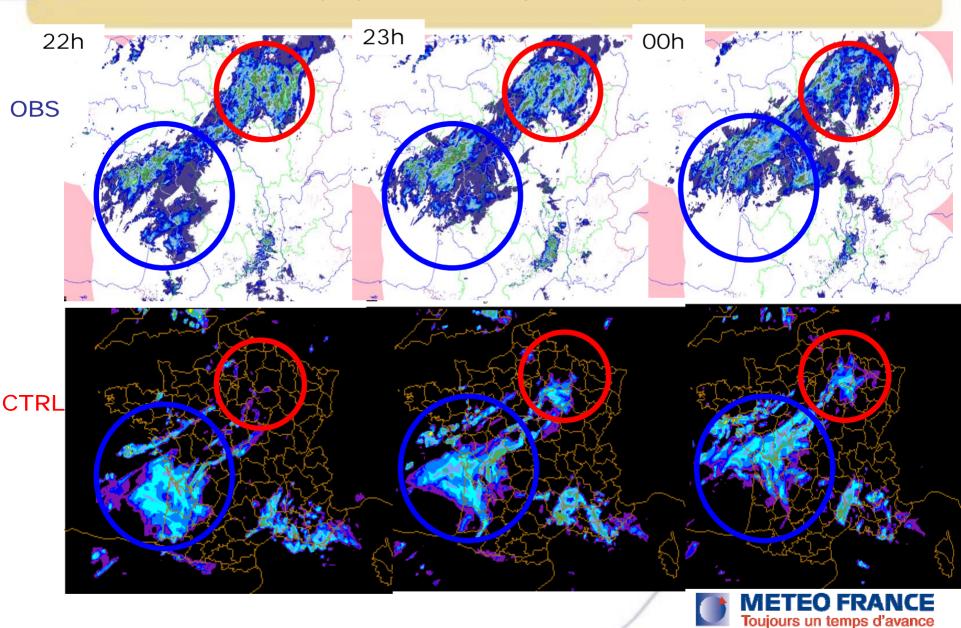


20 November 2007



19/20 Nov. 2007 – 1. Radar observations (OBS) AGAINST simulated reflectivities from the AROME model:

2. From the reference run from 21h (r21h) with 3 assimilation cycles: RUC 3h (CTRL)

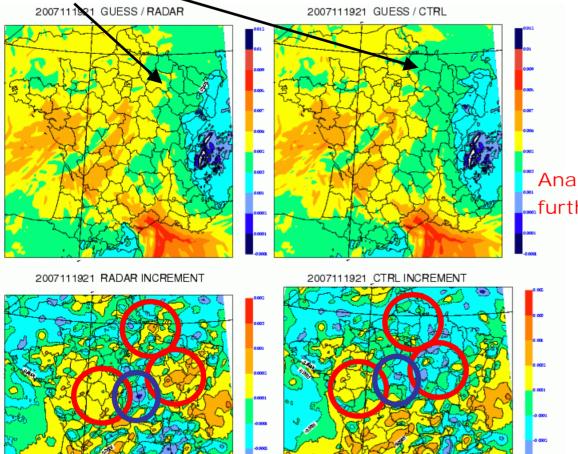




r21

MOSAÏC of assimilated radars at 21h

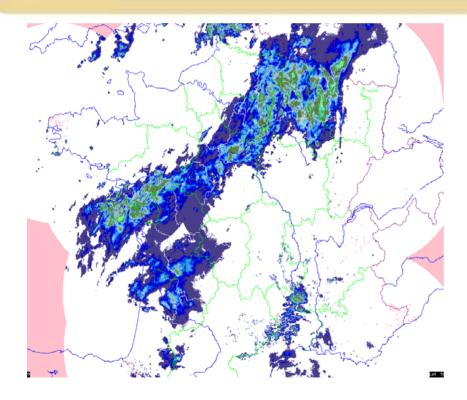
With assimilated reflectivities : guess is already humid on the North region



Analysis with radar increases

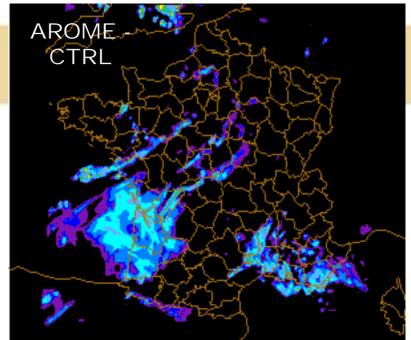
But is drying on the Centre France...

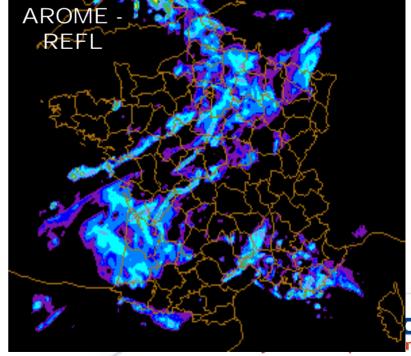


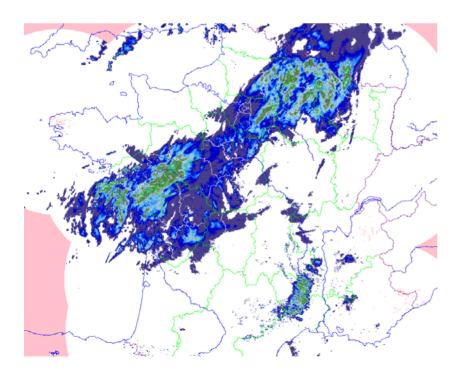


Instantaneous reflectivity field: 1h forecast

r21 - after 3 cyclages

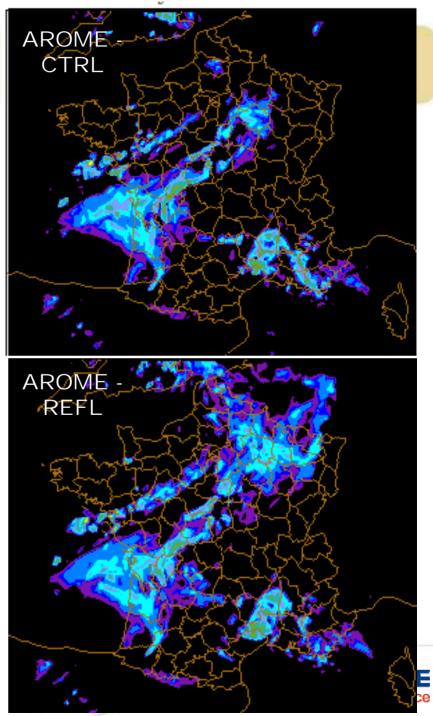


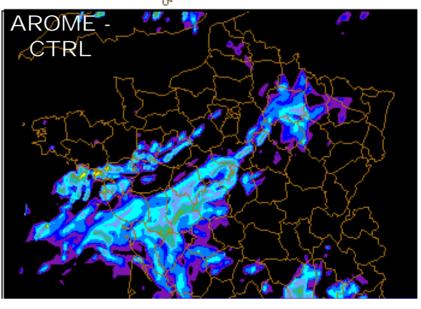




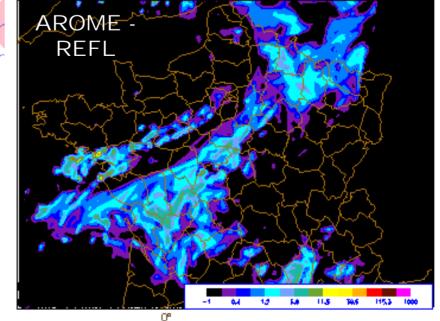
Instantaneous reflectivity field: 2h forecast

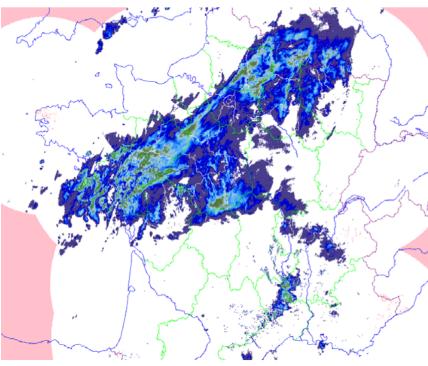
r21 - after 3 cyclages





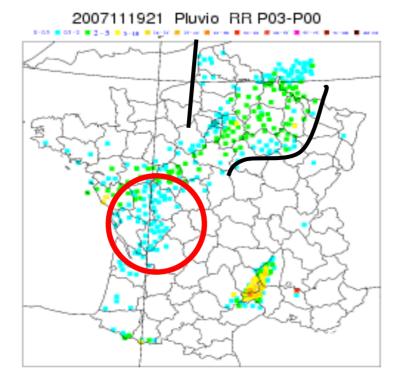
Monday 19 November 2007 21UTC PARIS - 1+3 VT; Tuesday 20 November 2007 00UTC Surfaces





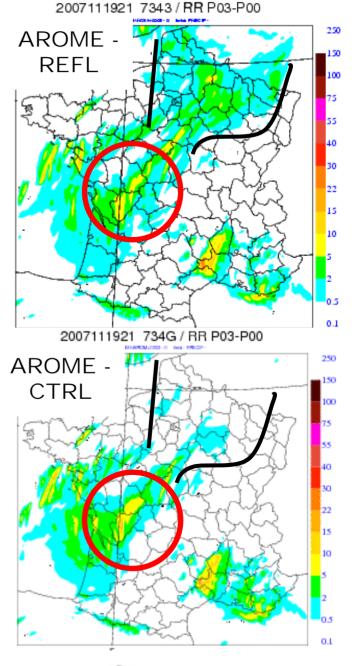
Instantaneous reflectivity field: 3h forecast

r21 - after 3 cyclages

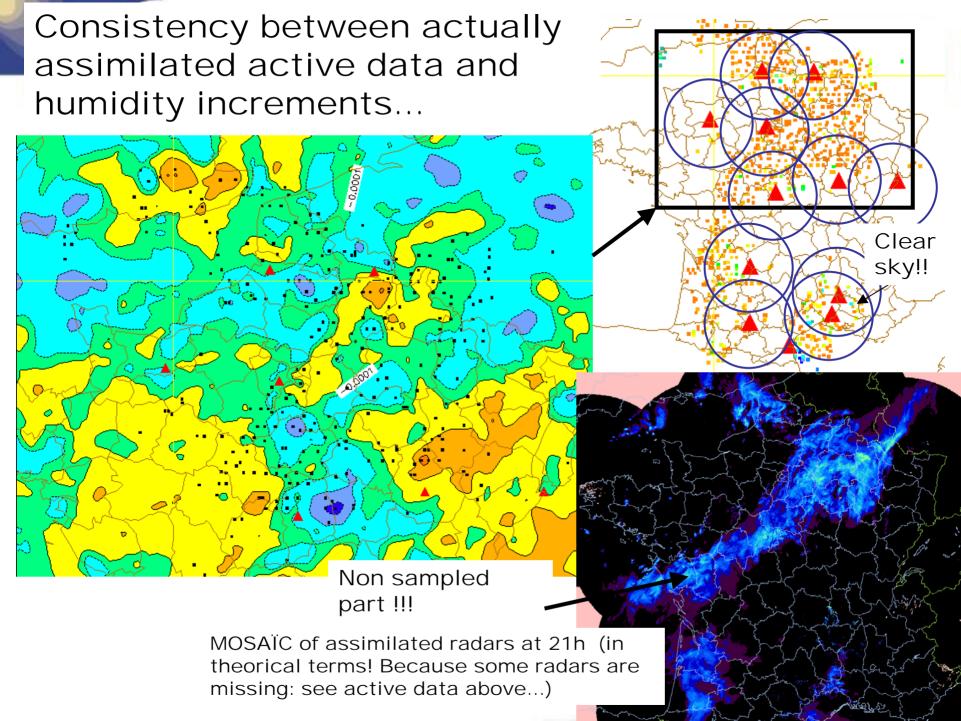


Verification : cumulated rain against rain-gauges

But difficult to dry up on the Southouest







Conclusion

1 décembre 2007:

- Good moving and setting of the cold front, capability of modifying the dynamic of the system.
- ☐ Visible impact on short range forecasts and also 12 hour forecast after initial time
- ☐ Better scores of humidity and cloud cover until 15 hour forecast

20 november 2007:

- Under a good sampling, capability of the assimilation method of reflectivities of creating precipitation and capability of drying up.
- ☐ little impact or non impact on rain forecasts after 12hour forecast (for this case, not shown here)



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- Towards the assimilation of radial winds: observation operator, quality control and thinning
- Towards the assimilation of reflectivities: observation operator, specific methodology for reflectivities, quality control, and thinning
- Assimilation status for reflectivities : results through case studies.
- Assimilation status for radial winds: results and impact on short forecasts through case studies.
- Conclusions and perspectives



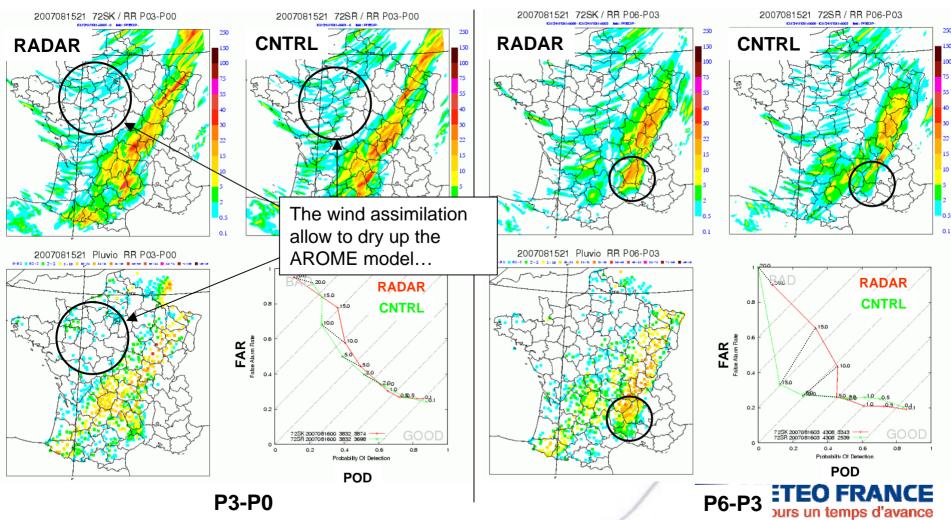
Doppler Winds assimilation 15 august 2007



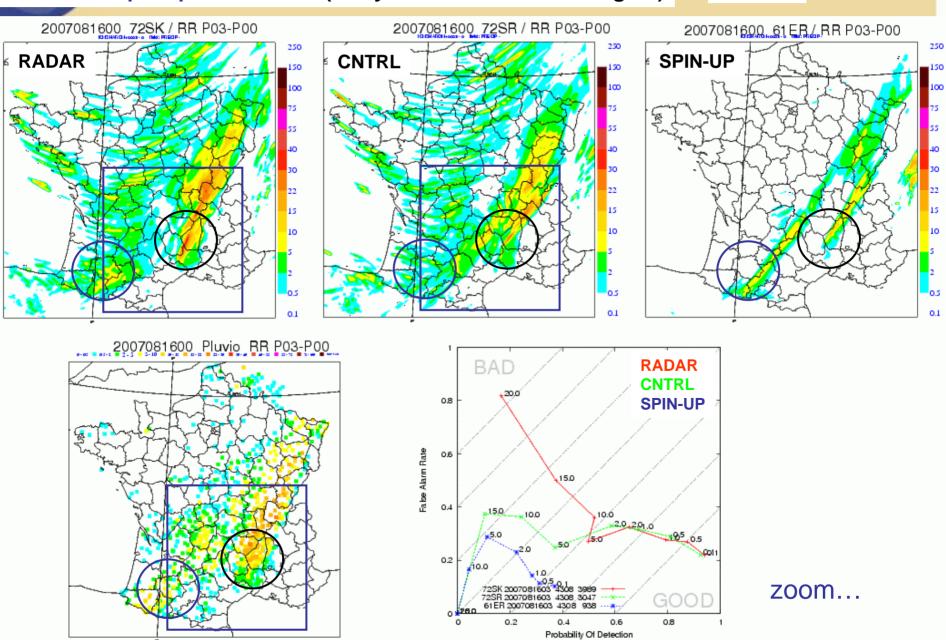
Se of 15 august 2007: heavy rain on cold front

- CNTRL: AROME with 3h-RUC, 1st analysis on 15 august at 9h
- RADAR: CNTRL with Doppler winds assimilated observed by 16 radars.

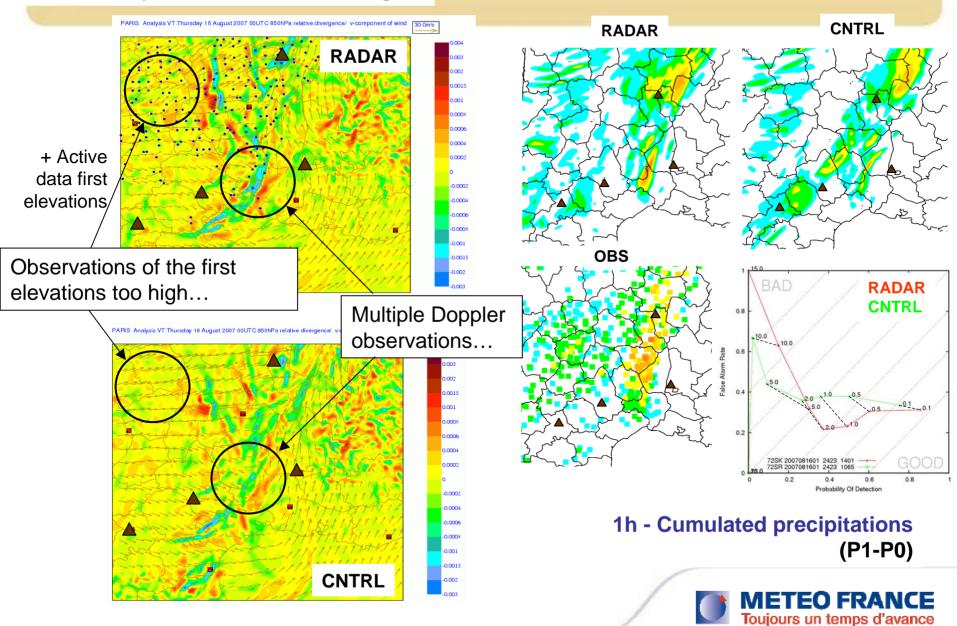
Précipitations cumulées sur 3h (analyse à 21 UTC)



P3-P0



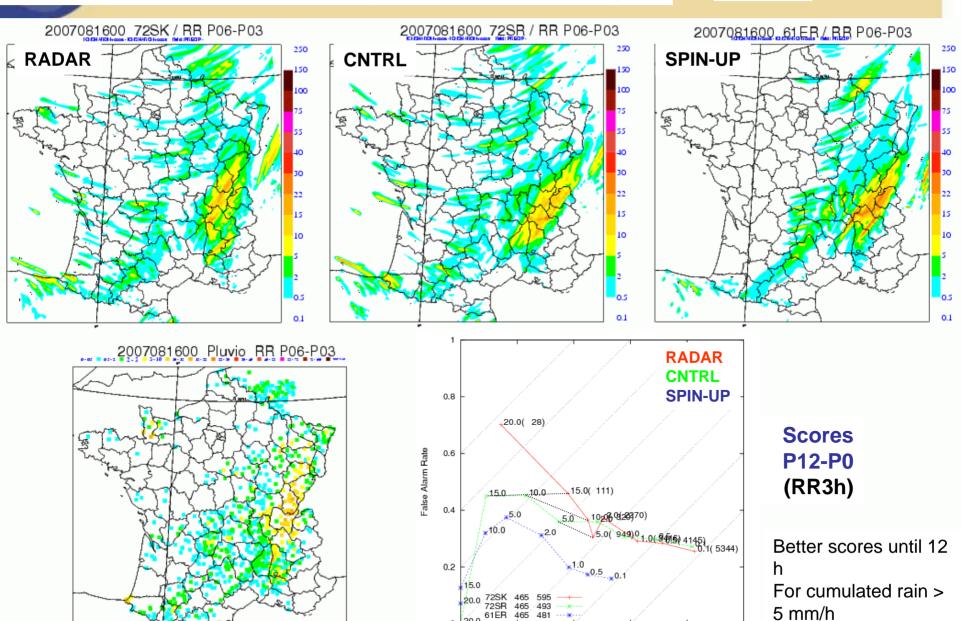
Divergence analysis(925 hPa) analysis at 00 UTC on 16 august



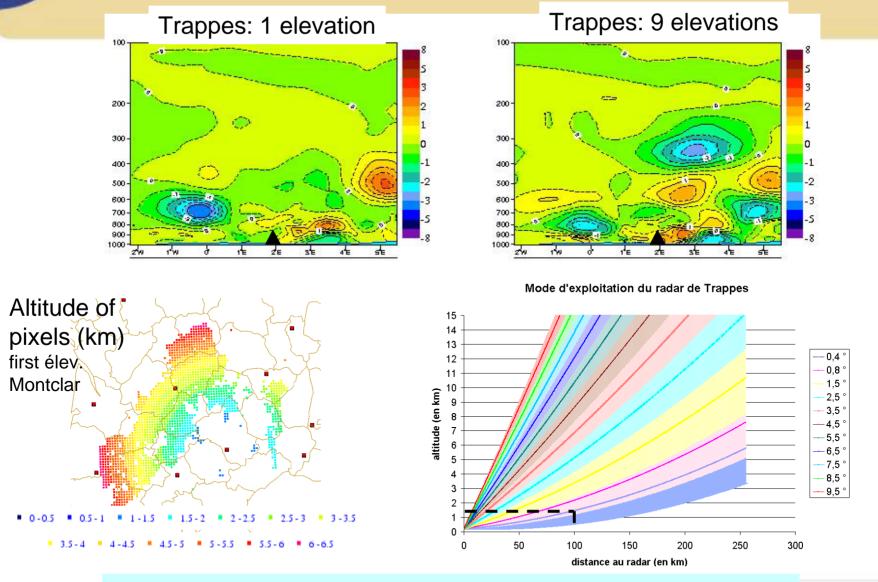
8.0

Probability Of Detection

3h Cumulated precipitations (analysis at 00 UTC the 16 august)



Winds Increments

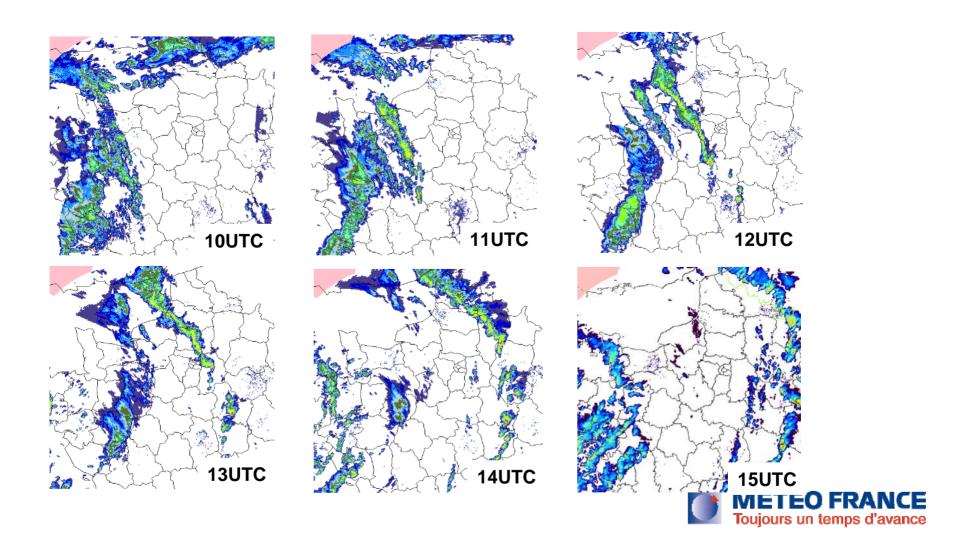


⇒ The convergence structures at low level of the atmosphere are only sampled near the radar



Case of 13 may 2007: squall line

- CNTRL: AROME with 3h-RUC, first analyse the 13 mai at 9h
- RADAR: CNTRL with Doppler winds assimilation observed by the radars of Trappes, Falaise, Abbeville, Avesnes, Blaisy, Troyes, Montclar

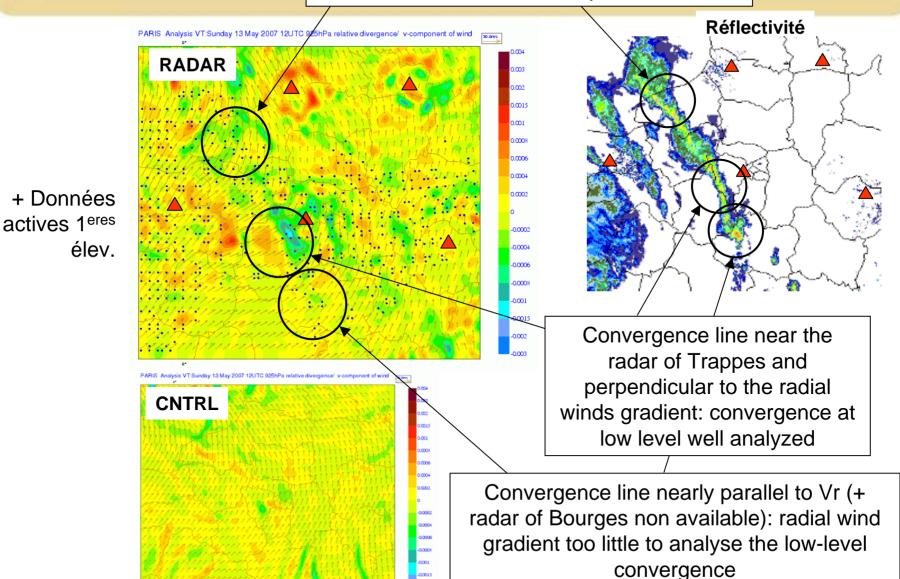


Divergence analysis (925 hPa) **12 UTC**

+ Données

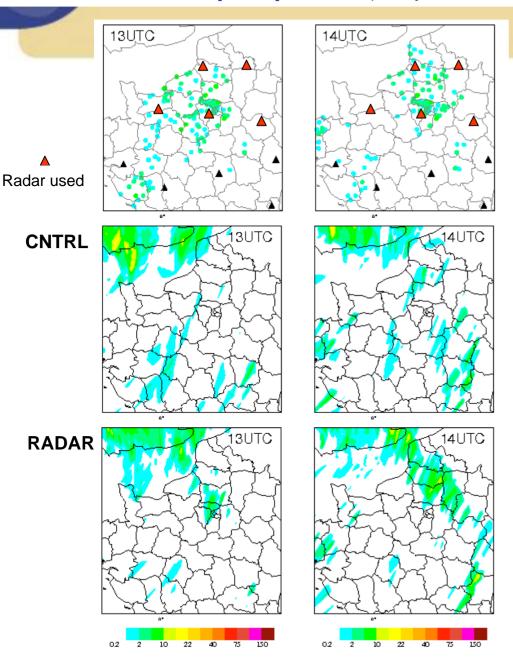
élev.

Convergence line at low level too far off the radars to be sampled



Toujours un temps d'avance

1h cumulated precipitation (analysis at 12 UTC)



- ⇒ Realistic forecast with radar, but: the forecast from 9h is not good because of distance with low level convergence
- ⇒ Squall line analyzed too late on Paris

⇒ The potentially positive impact of the assimilation of Vr for predicting convective systems depends heavily on the remoteness of radar systems and orientation gradients of Vr compared to structures convergence at low level

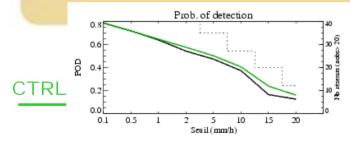


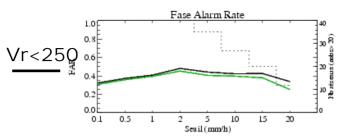
Conclusion

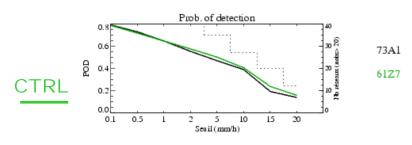
- ☐ A positif impact on forecasting precipitating patterns of convective systems has been observed when the convergence at low level is well sampled
- ☐ Realistic analysis of these structures of low level convergence have been obtained when:
 - these structures are near a radar
 - they are oriented perpendiculary at the radial wind gradient
 - they are sampled by several radars
- ☐ Large period of monitoring to assess the impact on the system currently under progress: promising results.

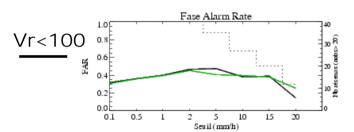


Monitoring and adjustments...

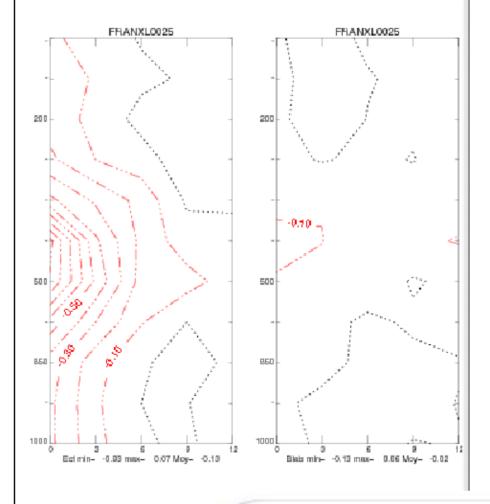








Winds: scores to analysis





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Conclusion, status and perspectives of radar assimilation

Radial winds: Continuous assimilation (over period of 1,5 mois) of doppler winds with an pre-operational assimilation AROME (each 3 hour, interesting for a systematic monitoring of doppler radars and AROME model).
☐ Many positive cases (QPF scores), neutral objectives scores, but some few negatives cases (subjective check): several adjustments to be done (decreasing the range, increase error statistics).
☐ results are sufficiently positive to predict winds will be incorporated into the first operational version of AROME
Reflectivities: ☐ Assimilation of reflectivities (separately) with cycling over periods of 4 or 5 days: cases studies and adjustments of the 1D+3DVar assimilation method.
☐ Method giving very often positive results (QPF scores), but currently sub- optimal, since removal of inverted profiles from the 1D method in cases of "bad convergence" (method fails because of a model "too far" from reality "radar"): work under progress to optimize the method.

Bibliography

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□Salonen, K., H. Järvinen, and M. Lindskog, 2003: Model for Doppler radar radial winds. <i>Proc.</i> 31 st Conf. On radar Met., Seattle, AMS, 142-145.
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☐ Probert-Jones J.R., 1962: The radar equation in meteorology. Quart. J. Roy. Meteor. Soc., Vol. 88, 485-495.
☐ Tabary P., L. Perier, J.Cagneux, and J.Parent-du-Châtelet, 2005: Test of a staggered PRT scheme for the French radar network. J.O.A.T., Vol. 22, 353-364
☐ Tabary P., F. Guibert, L. Perier, and J.Parent-du-Châtelet, 2006: An operational triple-PRT Doppler scheme for the French radar network, J.O.A.T., Vol. 23, 1645-1656

